

## **Web Appendix**

### **Retrieving Unobserved Consideration Sets from Household Panel Data**

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#### **Web Appendix A: Synthetic Data Analysis**

In this appendix, we show the results of a synthetic data analysis. We simulate data in a four-brand market, with 2446 observations. The data is generated according to a two-stage model, consisting of a multivariate probit consideration set formulation, followed by a multinomial probit brand choice model. We replicate the simulation using four sets of data-generating parameters. We eliminate the empty consideration sets from the data to mimic what happens in extant consideration sets models, which allow for empty consideration sets but do not use empty sets observations. Averaged across the replications, 1796 observations remain.

On the resulting dataset, we estimate our model, which takes into account that empty consideration sets might occur, and compare it to a benchmark model that uses a multivariate probit model in the consideration set stage that does not take into account that empty consideration sets are present in practice. The goal of this analysis is twofold:

- To show that our model can recover the DGP parameters well;
- To show that our model outperforms competing models when empty consideration sets are present, but not observed as is the case in most scanner panel datasets.

Table W1 shows the result of these simulations.

Table W1

Results of synthetic data analysis. Displayed are recovered parameters for our model (left panel) and a model that does not take empty consideration sets into account (right panel).

Variable	DGP	OUR MODEL		BENCHMARK MODEL	
	true	takes empty sets into account		does not take empty sets into account	
		M	SD	M	SD
<b>DGP 1</b>					
Intercept brand 1	-0.788	-0.831	0.133	-0.769	0.110
Intercept brand 2	-0.152	-0.392	0.163	-0.596	0.094
Intercept brand 3	-1.120	-1.880	0.181	-2.020	0.137
Intercept brand 4	-0.837	-0.848	0.116	-0.393	0.090
Display	1.321	1.500	0.108	1.020	0.067
Feature	1.821	2.080	0.261	1.280	0.109
<b>DGP 2</b>					
Intercept brand 1	0.000	0.0462	0.116	-0.141	0.0974
Intercept brand 2	-0.100	0.261	0.180	-0.936	0.084
Intercept brand 3	-0.200	-0.234	0.125	-1.752	0.104
Intercept brand 4	-0.300	-0.215	0.132	-0.271	0.087
Display	1.000	1.310	0.123	0.607	0.059
Feature	1.000	1.560	0.241	0.541	0.091
<b>DGP 3</b>					
Intercept brand 1	-0.500	-0.607	0.157	-0.769	0.091
Intercept brand 2	0.100	0.040	0.175	-1.024	0.067
Intercept brand 3	-1.000	-1.401	0.241	-2.37	0.115
Intercept brand 4	0.500	0.238	0.148	0.432	0.092

Display	2.000	1.750	0.198	0.988	0.069
Feature	2.000	2.341	0.236	0.646	0.095

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**DGP 4**

Intercept brand 1	-2.000	-2.102	0.169	-1.37	0.299
Intercept brand 2	0.100	0.207	0.231	-0.486	0.161
Intercept brand 3	-3.000	-3.373	0.296	-2.991	0.326
Intercept brand 4	0.500	0.465	0.141	0.405	0.319
Display	2.000	2.111	0.202	1.162	0.063
Feature	3.000	3.442	0.455	1.663	0.121

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The results show that the recovery of the brand consideration parameters is good for our proposed model. All 24 DGP-parameters are in the 99% HPD region of their respective estimates. For the model that does not allow empty consideration sets, this happens for only eight parameters.

## Web Appendix B: Full Conditional Posterior Distributions

In this appendix we provide the full conditional posterior distributions and sampling algorithms of the model parameters and the unobserved utilities.

### Sampling of $\alpha$

To obtain the full conditional posterior distribution of  $\alpha$  we rewrite (1) as

$$(1) \quad \Sigma^{-\frac{1}{2}}(C_{it}^* - X_{it}\alpha_i) = \Sigma^{-\frac{1}{2}}X_{it}\alpha + \Sigma^{-\frac{1}{2}}\varepsilon_{it},$$

where  $X_{it} = (X_{it1}, \dots, X_{itI})'$ , for  $i=1, \dots, I$  and  $t=1, \dots, T_i$ . We can interpret Equation 1 as  $J$  regression equations with regression coefficient  $\alpha$  and uncorrelated normally distributed error terms with unit variance. In total we have  $J \times \sum_{i=1}^I T_i$  of such regression equations. Hence, the full conditional posterior distribution of  $\alpha$  given  $\{\alpha_i\}_{i=1}^I$ ,  $\Sigma$  and  $C^*$  is normal. The mean and variance result from the OLS estimator of  $\alpha$  in (1), see Zellner (1971, Chapter VIII).

### Sampling of $\alpha_i$

To sample  $\alpha_i$  for  $i=1, \dots, I$  we can follow a similar approach as for  $\alpha$ . We rewrite Equation 1 as

$$(2) \quad \begin{aligned} \Sigma^{-\frac{1}{2}}(C_{it}^* - X_{it}\alpha) &= \Sigma^{-\frac{1}{2}}X_{it}\alpha_i + \Sigma^{-\frac{1}{2}}\varepsilon_{it} \quad \text{for } t = 1, \dots, T_i \\ \mathbf{0} &= \Sigma_{\alpha}^{-\frac{1}{2}}\alpha_i + \Sigma_{\alpha}^{-\frac{1}{2}}v_i. \end{aligned}$$

The last line follows from the fact that  $\alpha_i \sim N(\mathbf{0}, \Sigma_{\alpha})$  can be written as  $v_i = (\alpha_i - \mathbf{0}) \sim N(\mathbf{0}, \Sigma_{\alpha})$ . This represents  $k_X + JT_i$  regression equations with regression coefficient  $\alpha_i$  and uncorrelated normally distributed error terms with unit variance. Hence, the full conditional posterior distribution of  $\alpha_i$  given  $\alpha$ ,  $\Sigma_{\alpha}$ ,  $\Sigma$  and  $C^*$  is normal. The mean and variance result from the OLS estimator of  $\alpha_i$  in Equation 2.

### Sampling of $\Sigma_{\alpha}$

For the diagonal elements of  $\Sigma_{\alpha}$  it holds that

$$(3) \quad p(\sigma_{\alpha, kk}^2 | \cdot) \propto (\sigma_{\alpha, kk}^2)^{-(1+J)} \exp\left(-\frac{1}{2\sigma_{\alpha, kk}^2} \sum_{i=1}^I \alpha_{ik}^2\right),$$

for  $k = 1, \dots, k_X$ , where  $\alpha_{ik}$  is the  $k^{\text{th}}$  element of  $\alpha_i$ . Hence, the diagonal elements of  $\Sigma_\alpha$  can be sampled according to

$$(4) \quad \frac{\sum_{i=1}^I \alpha_{ik}^2}{\sigma_{\alpha, kk}^2} \sim \chi^2(I) \quad \text{for } k = 1, \dots, k_X.$$

### Sampling of $\Sigma$

To sample  $\Sigma$  we note that

$$(5) \quad p(\Sigma | \cdot) \propto \pi(\Sigma) = |\Sigma|^{-\frac{1}{2} \sum_{i=1}^I T_i} \exp\left(-\frac{1}{2} \sum_{i=1}^I \sum_{t=1}^{T_i} (C_{it}^* - X_{it}(\alpha + \alpha_i))' \Sigma^{-1} (C_{it}^* - X_{it}(\alpha + \alpha_i))\right),$$

for  $t=1, \dots, T_i$  and  $i=1, \dots, I$ .

As  $\Sigma$  is not a free covariance matrix (the diagonal elements are 1), the full conditional distribution is not inverted Wishart. In fact the full conditional posterior distribution of  $\Sigma$  is not standard. To sample  $\Sigma$  we propose a sampler based on Besag and Green (1993) and Damien, Wakefield and Walker (1999). Loosely speaking, this sampler interchanges the two steps in the Metropolis-Hastings sampler. A possible Metropolis-Hastings sampler for  $\Sigma$  is:

- Step 1 Draw the elements of the matrix  $\Sigma$  from a uniform distribution on the interval  $(-1, 1)$  under the restriction of positive definiteness, resulting in  $\Sigma^{\text{new}}$ .
- Step 2 Draw  $u$  from a uniform distribution on the interval  $(0, 1)$  and accept  $\Sigma^{\text{new}}$  if  $\pi(\Sigma^{\text{new}}) / \pi(\Sigma^{\text{old}}) > u$ . Otherwise take  $\Sigma^{\text{new}} = \Sigma^{\text{old}}$ .

For the sampler used in this paper we interchange these two steps. We first draw  $u$  from a uniform distribution on the interval  $(0, 1)$ . In the second step we keep sampling candidate draws of the elements of  $\Sigma$  from a uniform distribution on the interval  $(-1, 1)$  until  $\Sigma^{\text{new}}$  is positive definite and  $\pi(\Sigma^{\text{new}}) / \pi(\Sigma^{\text{old}}) > u$ . The advantage of the latter approach is that it always results in a new draw, which is not the case for the Metropolis-Hastings sampler, see Damien, Wakefield and Walker (1999) for details. The disadvantage is that the sampler is slower as one has to draw new candidates until acceptance. Another possibility to generate  $\Sigma$  based on the Metropolis-Hastings sampler is given in Chib and Greenberg

(1998) or the hit-and-run algorithm in Manchanda et al. (1999).

### Sampling of $\beta$

In the brand choice model,  $\beta$  is sampled in a similar way as  $\alpha$ . We rewrite Equation 4 as

$$(6) \quad \omega_j^{-1}(U_{ijt} - W'_{ijt}\beta_i) = \omega_j^{-1}W'_{ijt}\beta + \omega_j^{-1}\eta_{ijt},$$

for  $j=1,\dots,J$ ,  $i=1,\dots,I$  and  $t=1,\dots,T_i$ . This represents  $J \times \sum_{i=1}^I T_i$  regression equations with regression coefficient  $\beta$  and uncorrelated normally distributed error terms with unit variance. Hence, the full conditional posterior distribution of  $\beta$  given  $\{\beta_i\}_{i=1}^I$ ,  $\Omega$  and  $U$  is normal. The mean and variance result from the OLS estimator of  $\beta$  in (6), see again Zellner (1971, Chapter VIII).

### Sampling of $\beta_i$

To sample  $\beta_i$  for  $i=1,\dots,I$  we can follow a similar approach as for  $\beta$ . We rewrite Equation 4 as

$$(7) \quad \begin{aligned} \omega_j^{-1}(U_{ijt} - W'_{ijt}\beta) &= \omega_j^{-1}W'_{ijt}\beta_i + \omega_j^{-1}\eta_{ijt} \\ \mathbf{0} &= \Sigma_{\beta}^{-\frac{1}{2}}\beta_i + \Sigma_{\beta}^{-\frac{1}{2}}\mathbf{v}_i, \end{aligned}$$

for  $j=1,\dots,J$ ,  $i=1,\dots,I$  and  $t=1,\dots,T_i$ . The last line follows from the fact that  $\beta_i \sim N(\mathbf{0}, \Sigma_{\beta})$  can be written as  $\mathbf{v}_i = (\beta_i - \mathbf{0}) \sim N(\mathbf{0}, \Sigma_{\beta})$ .

This represents  $k_W + JT_i$  regression equations with regression coefficient  $\beta_i$  and uncorrelated normally distributed error terms with unit variance. Hence, the full conditional posterior distribution of  $\beta_i$  given  $\beta$ ,  $\Sigma_{\beta}$ ,  $\Omega$ , and  $U$  is normal. The mean and variance result from the OLS estimator of  $\beta_i$  in (7).

### Sampling of $\Sigma_{\beta}$

For the diagonal elements of  $\Sigma_{\beta}$  it holds that

$$(8) \quad p(\sigma_{\beta, kk}^2 | \cdot) \propto (\sigma_{\beta, kk}^2)^{-(l+1)} \exp\left(-\frac{1}{2\sigma_{\beta, kk}^2} \sum_{i=1}^l \beta_{ik}^2\right),$$

for  $k=1,\dots,k_W$ , where  $\beta_{ik}$  is the  $k^{\text{th}}$  element of  $\beta_i$ . Hence, the diagonal elements of  $\Sigma_{\beta}$  can be sampled according to

$$(9) \quad \frac{\sum_{i=1}^I \beta_{ik}^2}{\sigma_{\beta,kk}^2} \sim \chi^2(I) \quad \text{for } k = 1, \dots, k_w.$$

### Sampling of $\Omega$

To sample the elements of the covariance matrix  $\Omega$  we use that

$$(10) \quad p(\omega_j^2 | \cdot) \propto (\omega_j^2)^{-(\nu+1)} \exp\left(-\frac{1}{2\omega_j^2} \sum_{i=1}^I \sum_{t=1}^{T_i} (U_{ijt} - W_{ijt}'(\beta + \beta_i))^2\right)$$

with  $\nu = \sum_{i=1}^I T_i$  and hence

$$(11) \quad \frac{\sum_{i=1}^I \sum_{t=1}^{T_i} (U_{ijt} - W_{ijt}'(\beta + \beta_i))^2}{\omega_j^2} \sim \chi^2(\nu)$$

for  $j=1, \dots, J-1$ .

### Sampling of $U$

To sample  $U_{it}$  for  $i=1, \dots, I$  and  $t=1, \dots, T_i$  we consider

$$(12) \quad U_{it} = W_{it}(\beta + \beta_i) + \eta_{it}$$

and hence  $U_{it}$  is normally distributed with mean  $W_{it}(\beta + \beta_i)$  and covariance matrix  $\Omega$ . The conditional distribution of  $U_{ijt}$  given  $(U_{i1t}, \dots, U_{i,j-1,t}, U_{i,j+1,t}, \dots, U_{iIt})$  is of course also normal with, let's say, mean  $m_j$  and variance  $s_j^2$ . Hence,  $U_{ijt}$  can be sampled from truncated normal distributions in the following way

$$(13) \quad U_{ijt} | \cdot \sim \begin{cases} N(m_j, s_j^2) \times I(-\infty, U_{i,d_{it},t}) & \text{if } j \neq d_{it} \wedge c_{ijt} = 1 \\ N(m_j, s_j^2) \times I(\max_{k|k \neq j} (U_{ikt} | c_{ikt} = 1), \infty) & \text{if } j = d_{it} \\ N(m_j, s_j^2) \times I(-\infty, \infty) & \text{if } c_{ijt} = 0, \end{cases}$$

for  $j=1, \dots, J$ , see Geweke (1991) for details. The value of  $c_{ijt}$  is of course determined by the values of the draws of  $C_{ijt}^*$ .

### Sampling of $C^*$

To sample  $C_{it}^*$  for  $i=1, \dots, I$  and  $t=1, \dots, T_i$  we consider

$$(14) \quad C_{it}^* = X_{it}(\alpha + \alpha_i) + \varepsilon_{it}$$

and hence  $C_{it}^*$  is normally distributed with mean  $X_{it}(\alpha + \alpha_i)$  and covariance matrix  $\Sigma$ . The conditional distribution of  $C_{ijt}^*$  given  $(C_{1it}^*, \dots, C_{i,j-1,t}^*, C_{i,j+1,t}^*, \dots, C_{iT}^*)$  is in this case also normal with, let say, mean  $m_j$  and variance  $s_j^2$ , for  $j=1, \dots, J$ . We need to distinguish four situations for the sampling of  $C_{ijt}^*$  for  $j=1, \dots, J$ :

1. The first situation corresponds to  $j = d_{it}$ . In this case we sample

$$(15) \quad C_{ijt}^* | \cdot \sim \begin{cases} N(m_j, s_j^2) \times I(0, \infty) & \text{if } \sum_{k=1, k \neq j}^J c_{ikt} > 0 \\ N(m_j, s_j^2) \times I(\max_{k|k \neq j} (C_{ikt}^*), \infty) & \text{if } \sum_{k=1, k \neq j}^J c_{ikt} = 0. \end{cases}$$

2. The second situation corresponds to  $j \neq d_{it}$  and  $U_{ijt} > U_{i,d_{it},t}$ , in which case we sample

$$(16) \quad C_{ijt}^* | \cdot \sim \begin{cases} N(m_j, s_j^2) \times I(-\infty, 0) & \text{if } \sum_{k=1, k \neq j}^J c_{ikt} > 1 \\ N(m_j, s_j^2) \times I(-\infty, \min(0, C_{i,d_{it},t}^*)) & \text{if } \sum_{j=1, k \neq j}^J c_{ikt} = 1. \end{cases}$$

3. The third situation corresponds to  $j \neq d_{it}$  and  $U_{ijt} < U_{i,d_{it},t}$  with  $C_{i,d_{it},t}^* < 0$ . In this case we sample

$$(17) \quad C_{ijt}^* | \cdot \sim N(m_j, s_j^2) \times I(-\infty, C_{i,d_{it},t}^*).$$

4. In all other cases we use the following approach:

$$(18) \quad C_{ijt}^* | \cdot \sim N(m_j, s_j^2).$$

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